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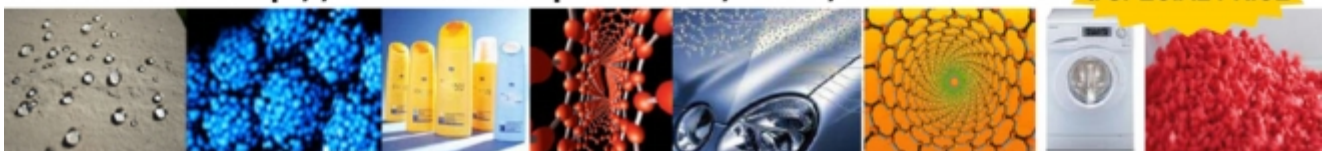
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Angle-tip Fiber Probe as Humidity Sensor

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Abstract: In this paper, I present a simple fiber optic relative humidity sensor (FORHS) using an angled-tip multimode optical fiber. The sensing region is fabricated by coating moisture sensitive Cobalt Chloride (CoCl_2) doped polyvinyl alcohol (PVA) film on the surface of fiber optic tip. Light signal introducing from flat-end of the fiber is back-reflected at the fiber tip-air interface by the effect of total internal reflection. The change of relative humidity (RH) in the outstanding medium affects of evanescent field absorption at the fiber tip-sensing film interface thus, modulates the back-reflected signal. With the present sensing investigation, RH ranging from 5 % to 95 % can be measured with high degree of repeatability and has a fast response time of about 2 seconds. *Copyright © 2010 IFSA.*

Keywords: Fiber optic sensor, Relative humidity, Angled-tip fiber probe

1. Introduction

Humidity monitoring is critical for different industrial and laboratory applications. Presence of high level of humidity affects the quality of products and performance of devices installed in various environments. For instance, in microelectronic industries, the performance of many electronic devices is seriously affected by high level of humidity present in the environment. Again, in tea industries, proper level of RH in drier chamber determines the quality of tea yields from the industry. Practical realization of RH sensor is rather a difficult task as this has to be in direct contact with the process environment. There are number of FORHSs that have been reported and demonstrated by different researchers [1-6] in the recent past. In most of these sensors, a moisture sensitive chemical is coated on an unclad region of the optical fiber and variation of evanescent wave absorption due to the presence of moisture in the outstanding medium is monitored for RH sensing investigation. Anhydrous CoCl_2 is one of the most commonly used chemical for this purpose. Anhydrous CoCl_2 is blue and has a strong

absorption in the wavelength range of 550-750 nm when it is dry. However, as it interacts with the moisture present in air it turns in to pink (~680nm) showing excellent transmission in that particular wavelength range. Absorption spectrum of CoCl_2 in gelatin at different humidity level is described in [6]. FORHSs based on unclad U-bent sensing region [2] or straight unclad fiber sensing region [4] work well in the RH range of 20 % to 75 %. However, such sensing region is fragile and has to be very handled very carefully because little stress experiencing on it may permanently damage the optical fiber. Hence, an unclad fiber may not always safe and suitable for RH sensing applications. In recent years, optical fibers with one end either an angle-polished or curve shaped fiber tips have been extensively studied for measurement of various parameters [7-10]. Compared to U-bent or a straight unclad FORHS, an angled tip [8] fiber probes offer advantages in terms of:

- i). better geometrical flexibility;
- ii). can be used as a probe for RH sensing investigation;
- iii). sensing scheme is more robust for handling;
- iv). RH variation in a small volume of environment can be measured.

In the present work, a simple high dynamic range RH sensor with high sensitivity using an angled-tip multimode optical fiber is demonstrated. The fiber tip is coated with moisture sensitive CoCl_2 doped PVA film. Light signal propagating from flat-end of the fiber is back-reflected at the fiber tip-air interface by the effect of total internal reflection. The change of humidity surrounding the sensing region of the fiber modulates the back-reflected light signal. With the present sensing scheme humidity variation in the range of 5 % to 95 % can be measured with high degree of repeatability and has a fast response time of about 2 seconds.

2. Sensing Principle

Fig. 1 shows the fiber sensing tip for the present investigation. The FORHS presented here is an intrinsic type sensor. The sensing principle of the present FORHS is based on intensity modulation of back-propagated light signal from an angled-shape fiber tip which has been coated with moisture sensitive PVA/ CoCl_2 film. Light signal propagating from the flat-end of the fiber undergoes total internal-reflection at the fiber tip-air interface and would reflect back to the entry port of the fiber. The critical angle condition for the total internal reflection to occur is given by

$$\theta_c(\lambda) = \arcsin [n_a(\lambda)/n_1(\lambda)] \quad (1)$$

Here, $n_1(\lambda)$ is the refractive index of the fiber core which is a wavelength dependant quantity and $n_a(\lambda)$ is the index of refraction of the external medium surrounding the fiber sensing tip. For, the present case we have used sensor grade step-index multimode optical fiber of core/cladding diameter 980/1000 μm with $n_1(\lambda) = 1.4673$ and $n_a(\lambda) = 1$ thus, giving $\theta_c(\lambda) \sim 43^\circ$.

For present sensing investigation the fiber tip is polished to an angle greater than the critical angle (43°) thus, most of the forward going modes will be back-reflected to the entry port of the fiber. The sensing region was dip-coated with 3% CoCl_2 doped in 1% PVA solution and was allowed to dry for 24 hours followed by annealing at 60° Centigrade for 2 hours. For light signal propagating from flat-end of the fiber, there would be evanescent wave absorption at the fiber sensing tip- sensing film interface. The change of RH in the outstanding medium affects the evanescent wave absorption of the back-reflected light signal and thus, modulates the irradiance of the light signal. Since all the back-reflected light modes interact with the sensing region of the fiber, the present technique is found to be sensitive than that of an unclad FORHS [4] where some of the selected modes were involved for interaction

with RH in the medium. For the present case, I use 2-dip and 3-dip coating film on the sensing region of the fiber.



Fig. 1. (a) Photograph of an angled-tip optical fiber; (b) Magnified view of photo (a). For dimensional comparison a 5 rupees coin is also shown in the photograph. The angle of the fiber tip was measured to be 50° .

3. Experimental Arrangement

Experimental arrangement for the present sensing investigation is shown in Fig. 2. Light signal from an intensity stabilized laser source ($\lambda = 670\text{nm}$, 5mW) is coupled to the flat-end of the optical fiber through an objective O. The sensing tip of the fiber is placed inside a plexiglass climate chamber. Using a beam splitter the useful back-reflected light signal from the sensing region is directed to the detector (photodiode). For rapid humidity variation, a small volume of climate chamber is taken with moisture inlet (MI) and outlet (MO) provision. For calibration, a standard resistive based digital electronic hygrometer is kept inside the climate chamber.

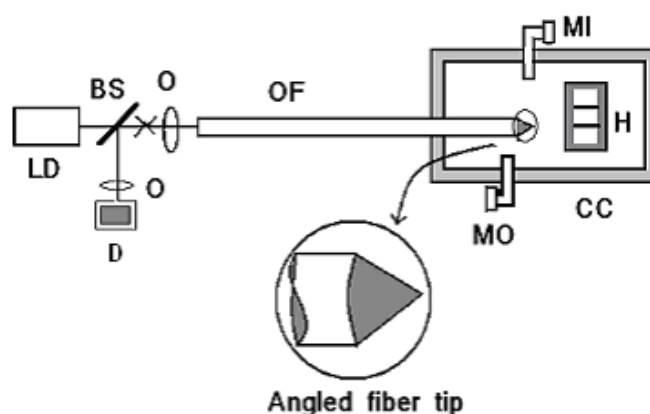


Fig. 2. Schematic of the experimental set-up for RH sensor: LD laser diode; BS beam splitter; O objective; OF optical fiber; H hygrometer; MI moisture inlet; MO moisture outlet; CC climate chamber; D detector.

4. Results and Discussion

To study the characteristics of the present sensor, initially low humidity level was maintained inside the chamber. To obtain low level of humidity, initially calcium sulphate is introduced inside the climate chamber and humidity level down to 5 % has been achieved. Moisture contained air is then

gradually introduced through the MI of the climate chamber. The change of humidity level and the corresponding sensor response for 2-dip coated fiber tip with time is shown in Fig. 3.

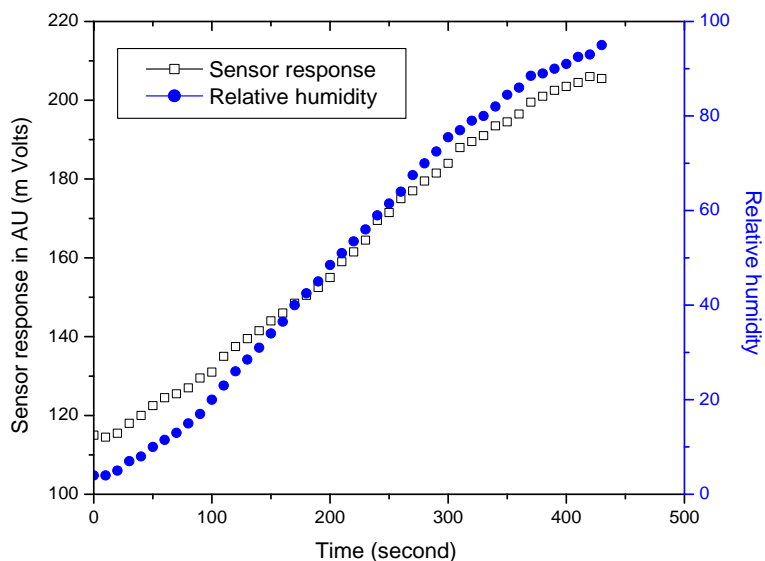


Fig. 3. Sensor response curve for 2-dip coated film with humidity variation inside the climate chamber.

With the increase of RH inside the chamber, the absorbance of the CoCl_2/PVA film decreases and thus higher back-reflected signal would be received by the photodiode. The investigation is also carried out for 3-dip coated fiber tip and the normalized sensor response for these two films are shown in Fig. 4. This variation clearly indicates that with increasing film thickness the sensitivity (the fractional change in power per unit change in relative humidity) of the sensor response increases with film thickness as now more CoCl_2 molecule would be available per unit area in the sensing region. However, optimum signal modulation and hence sensitivity would be achieved when penetration depth of the evanescent field at the fiber tip matches with the sensing film thickness.

We then investigate the sensor response for another angle-tip fiber maintained at 80° with same fiber core diameter. A comparative study of the sensor response for two cases. 50° and 80° angled sensor tips are shown in Fig. 5. For 80° angled-tip optical fiber, less area of the sensing region is exposed to moisture environment thus, yields lower sensitivity and dynamic range than to a 50° angled fiber tip. In the present case, highest sensitivity and dynamic range would be possible for fiber angle-tip which has maximum back-reflectance light signal and large sensing area for exposure to the moisture environment. Thus, a fiber tip of 45° angle would have maximum back-reflectance light signal and the largest sensing area for exposure to the environment. Hence, optimum level of sensitivity and dynamic range can be expected for this tip.

To study to repeatability behavior of the sensor moisture contained compressed air is introduced slowly into the climate chamber and sensor characteristic is observed for both increasing and decreasing cycle of relative humidity inside the chamber. The sensor response was observed for 2-dip coated film with 50° angle fiber sensing tip. Three such cycles were taken and the graphical format of the obtained data is shown in the Fig. 6. This investigation was carried out several times and similar response was observed every time. Thus, good degree of repeatability is seen in the sensor.

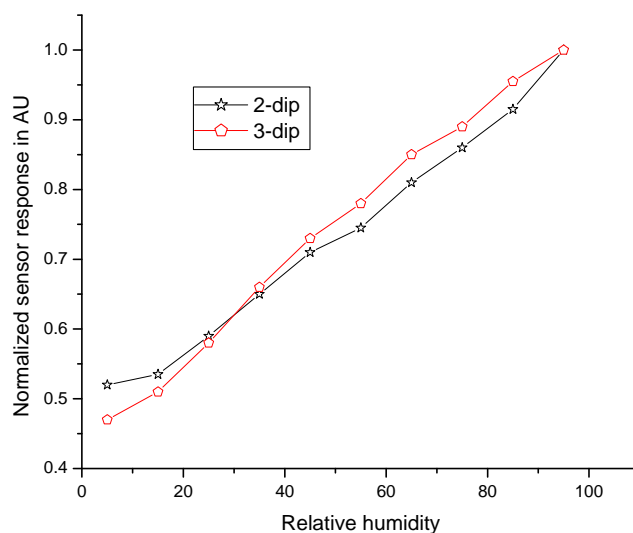


Fig. 4. Normalized sensor response for 2-dip and 3-dip coated film on fiber sensing tip.

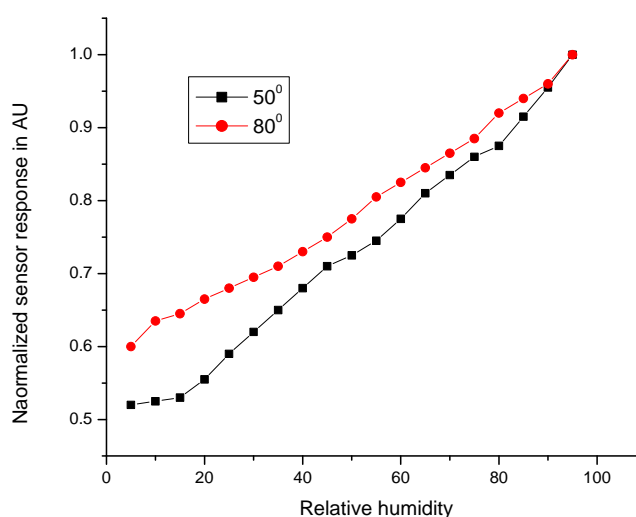


Fig. 5. Normalized Sensor response for two fiber angled tips maintained at 50° and 80°.

To measure the response time of the designed sensor, moisture contained pressurized air is rapidly introduced into the climate chamber and the corresponding sensor reading has found to be approximately of 2 seconds for responding each degree of change in humidity level inside the chamber in the RH range 35 % to 75 % while for humidity below 35 % and above 75 % it took approximately 5-6 seconds. The performance of the present sensor is to be investigated for different composition of CoCl₂ doped PVA solutions. The present technique can also be exploited for sensing of other parameters such as pH value, temperature etc. by coating suitable sensing chemicals on the fiber tip.

5. Conclusions

I present a novel technique for measurement of RH using angle-shaped fiber tip as sensing region and highlighted its advantages over the U-shaped probe fiber optic RH sensor. No comparative study of the present sensor has been performed with U-shaped fiber sensor or a side polished fiber sensor. The advantage of the technique is its flexibility and relative humidity in a small volume of environment can

be measured. Further compared to U shaped fiber probe, the sensing region of the present sensor is more robust for handling.

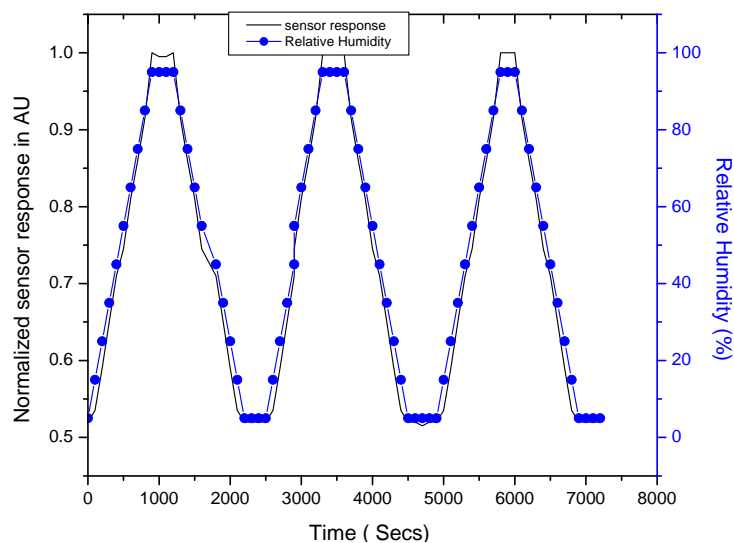


Fig. 6. Repeatability behavior of the fiber optic humidity sensor with 2-dip coated CoCl_2/PVA film angled-tip maintained at 50° .

Acknowledgement

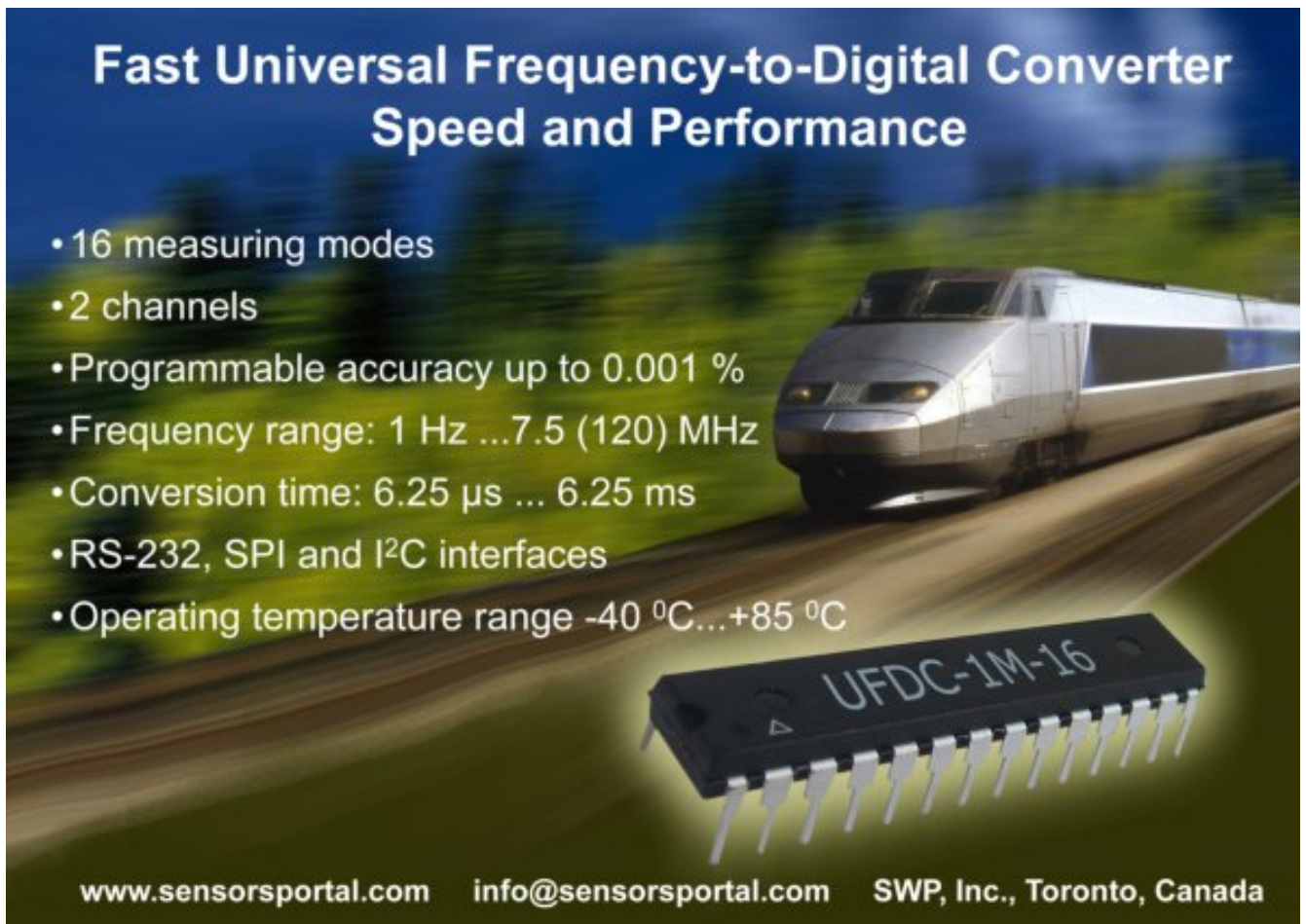
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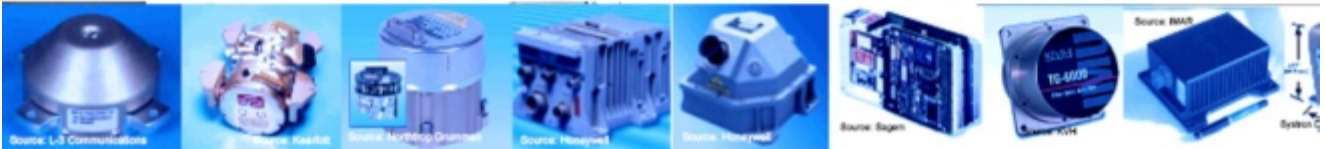
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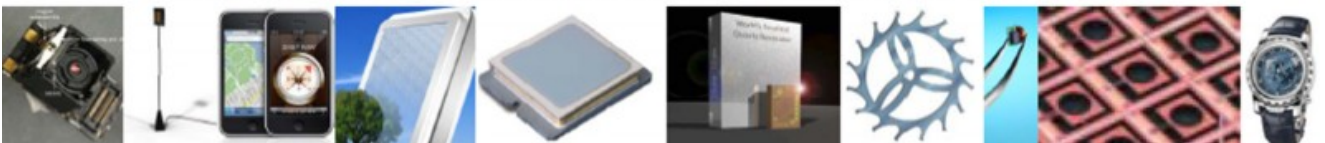
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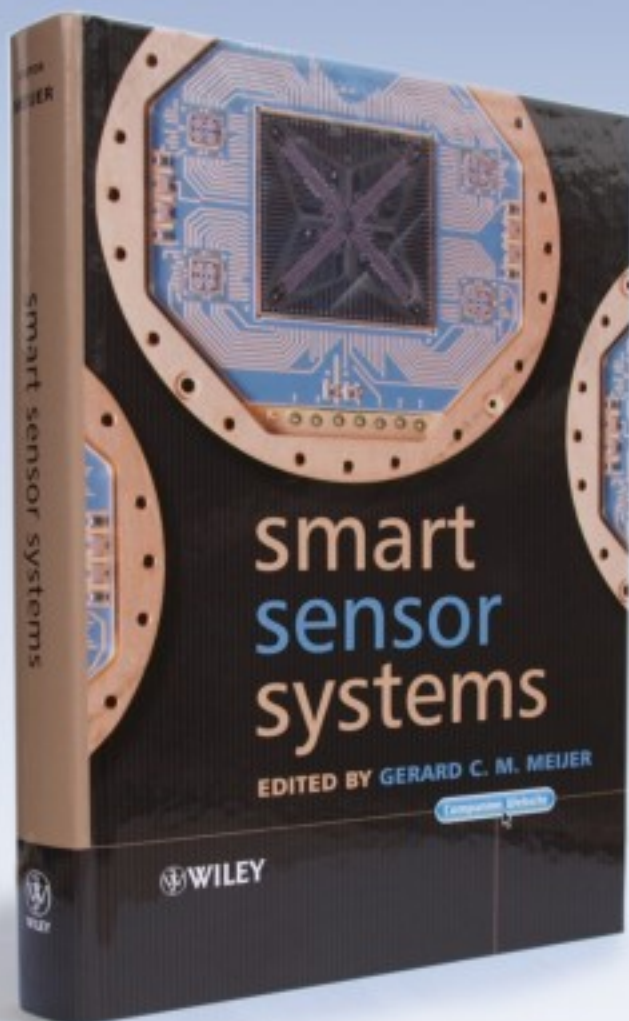
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